

Listing of the Claims:

1. (Currently Amended) An apparatus comprising:
a support structure having first and second arm portions formed thereon for movement relative to one another, and a secondary portion integrally formed on an outer end of each arm portion for movement therewith; and
a primary actuator operably associated with the support structure for driving the arm portions relative to one another in response to an electrical activation of the primary actuator, and a secondary actuator operably associated with each secondary portion for driving each secondary portion between an opened position and a closed position in response to an electrical activation of the secondary actuator, each of the actuators being operable independently of one another.
2. (Original) The apparatus of claim 1 further comprising:
a rigid non-flexing web portion associated with the support structure.
3. (Original) The apparatus of claim 1 further comprising:
a force transfer member portion for transmitting a force from the primary actuator to move the associated secondary portions between an extended position and a retracted position with respect to one another, the secondary portions moving toward one another to the retracted position when the primary actuator is de-energized and the secondary portions moving away from one another to the extended position when the primary actuator is energized.
4. (Original) The apparatus of claim 3 further comprising:
a rigid non-flexing web portion associated with outwardly extending side portions at opposite ends of the web portion defining a rigid non-flexing C-shaped portion of the support structure; and
a pair of hinge portions extending generally parallel to one another between the force transfer member portion and each arm portion of the support structure, and between the force transfer member portion and each side portion of the support structure.

5. (Original) The apparatus of claim 1, wherein each of the secondary portions further comprises:

a secondary web portion integrally associated with the corresponding arm portion of the support structure; and

first and second secondary arm portions integrally associated with and extending from opposite ends of each secondary web portion.

6. (Original) The apparatus of claim 5, wherein each of the secondary portions further comprises:

a force transfer member portion for transmitting a force from the secondary actuator to move the associated secondary arm portions between an opened position and a closed position with respect to one another, the secondary arm portions moving toward one another to the closed position when the secondary actuator is de-energized and the secondary arm portions moving away from one another to the opened position when the secondary actuator is energized.

7. (Original) The apparatus of claim 1, wherein each of the secondary portions further comprises a clamp portion.

8. (Original) The apparatus of claim 7, wherein each of the secondary portions further comprises opposing surfaces formed on each of the clamp portions with shaped recesses engagable with a movable member having a complementary shape.

9. (Original) The apparatus of claim 1, wherein each of the secondary portions further comprises a valve portion.

10. (Currently Amended) [[The]] An apparatus of claim 9, further comprising:

a support structure having first and second arm portions formed thereon for movement relative to one another, and a secondary portion integrally formed on an outer end of each arm portion for movement therewith, wherein each of the secondary portions further includes a valve portion, the secondary portions defining a first valve portion and a second valve portion;

a primary actuator operably associated with the support structure for driving the arm portions relative to one another in response to an electrical activation of the primary actuator, and a secondary actuator operably associated with each secondary portion for driving each secondary portion between an opened position and a closed position in response to an electrical activation of the secondary actuator, each of the actuators being operable independently of one another; and

an expandable positive displacement pumping chamber positioned between the first and second arm portions of the support structure and in fluid communication with the first valve portion and the second valve portion.

11. (Original) The apparatus of claim 1, wherein the primary and secondary actuators can be triggered in different sequential series for bi-directional operation.

12. (Original) The apparatus of claim 11, wherein the bi-directional operation is operable to move a movable member in either direction with respect to the support structure.

13. (Currently Amended) [[The]] An apparatus of claim 11 comprising:

a support structure having first and second arm portions formed thereon for movement relative to one another, and a secondary portion on an outer end of each arm portion for movement therewith; and

a primary actuator operably associated with the support structure for driving the arm portions relative to one another in response to an electrical activation of the primary actuator, and a secondary actuator operably associated with each secondary portion for driving each secondary portion between an opened position and a closed position in response to an electrical activation of the secondary actuator, each of the actuators being operable independently of one another, wherein the primary and secondary actuators can be triggered in different sequential series for bi-directional operation, wherein the bi-directional operation is operable to pump fluid in either direction with respect to the support structure.

14. (Original) The apparatus of claim 1, wherein the actuators are piezoelectric.

15. (Original) The apparatus of claim 1, wherein the actuators are magnetostrictive.

16. (Currently Amended) The apparatus of claim 1 further comprising: a first and second pair of substantially parallel hinges for the first and second ~~clamps~~ arm portions to pivot about respectively, the first and second pair of hinges formed by at least one reduced area created by slots located in the support structure between each ~~clamp and each side of the structure~~ arm portion, and between the force transfer member and the ~~clamps~~ arm portions.

17. (Original) The apparatus of claim 1, wherein the support structure is formed of homogenous material.

18. (Original) The apparatus of claim 1, wherein the support structure is a uni-body construction.

19. (Original) The apparatus of claim 1 further comprising:
means for preloading at least one of the primary and secondary actuators.

20. (Original) The apparatus of claim 19 wherein the preloading means further comprises:

a force focusing member operably associated with an end of the at least one of the primary and secondary actuators; and

a screw threadably engagable with a rigid end web of the support structure, the screw operably associated with the force focusing member such that a preload force can be applied to the actuator through the screw and force focusing member prior to energizing the actuator.

21. (Currently Amended) A method comprising the steps of:
energizing a primary actuator for moving first and second primary pivotable arm portions of a support structure from a first position adjacent one another to a second position spaced apart from one another;

energizing at least one secondary actuator for moving first and second secondary pivotable arm portions integrally formed with [[of]] the support structure

from a first position adjacent one another to a second position spaced apart from one another; and

sequentially energizing and de-energizing the primary and secondary actuators to perform work.

22. (Original) The method of claim 21 further comprising the steps of: opening a fixed clamp responsive to energization of a first secondary actuator, while a normally closed movable clamp remains closed at a start position on a movable member in response to a de-energized second secondary actuator;

moving the movable clamp away from fixed clamp responsive to energization of the primary actuator to carry the movable member to be moved with respect to the fixed clamp;

closing the fixed clamp in response to de-energization of the first secondary actuator;

opening the movable clamp in response to energization of the second secondary actuator; and

moving the movable clamp toward the fixed clamp in response to de-energization of the primary actuator to the start position prior to closing on the movable member.

23. (Currently Amended) [[The]] A method of claim 21 further comprising the steps of:

energizing a primary actuator for moving first and second primary pivotable arm portions of a support structure from a first position adjacent one another to a second position spaced apart from one another;

energizing at least one secondary actuator for moving first and second secondary pivotable arm portions of the support structure from a first position adjacent one another to a second position spaced apart from one another;

sequentially energizing and de-energizing the primary and secondary actuators to perform work;

opening a first valve responsive to energization of a first secondary actuator, while a normally closed second valve remains closed in response to a de-energized second secondary actuator;

expanding a positive displacement pumping chamber responsive to energization of the primary actuator to draw fluid through the first valve into the chamber;

closing the first valve in response to de-energization of the first secondary actuator;

opening the second valve in response to energization of the second secondary actuator; and

contracting the positive displacement pumping chamber in response to de-energization of the primary actuator to force fluid within chamber through the second valve.

24. (New) An apparatus comprising:

a support structure having first and second arm portions movable relative to one another through an actuator-movement-amplification portion, and a secondary portion located on an outer end of each arm portion for movement therewith; and

a primary actuator operably associated with actuator-movement-amplification portion of the support structure for driving the arm portions relative to one another in response to an electrical activation of the primary actuator, and a secondary actuator operably associated with each secondary portion for driving each secondary portion between an opened position and a closed position in response to an electrical activation of the secondary actuator, each of the actuators being operable independently of one another.

25. (New) The apparatus of claim 24, wherein the actuator-movement-amplification portion of the support structure further comprises:

a rigid, non-flexing force transfer portion of the support structure located in opposition to an open end of a rigid, non-flexing C-shaped web portion of the support structure for supporting the primary actuator therebetween; and

hinge portions connecting the force transfer portion to the arm portions and the C-shaped web portion of the support structure, one pair of hinge portions extending between the force transfer member portion and each arm portion of the support structure, and another pair of hinge portions extending between the force transfer member portion and each side portion of the support structure.

26. (New) The apparatus of claim 24 further comprising:
each secondary portion of the support structure including an
actuator-movement-amplification portion.

27. (New) The apparatus of claim 26, wherein the
actuator-movement-amplification portion of at least one of the secondary portions of
the support structure further comprises:

a rigid, non-flexing force transfer portion of the secondary portion of
the support structure located in opposition to an open end of a rigid, non-flexing
C-shaped web portion of the secondary portion of the support structure for
supporting the corresponding secondary actuator therebetween; and

hinge portions connecting the force transfer portion to the arm portions
and the C-shaped web portion of the secondary portion of the support structure, one
pair of hinge portions extending between the force transfer member portion and each
arm portion of the secondary portion of the support structure, and another pair of
hinge portions extending between the force transfer member portion and each side
portion of the secondary portion of the support structure.

28. (New) An apparatus comprising:
a support structure having first and second arm portions movable
relative to one another, and a secondary portion located on an outer end of each arm
portion for movement therewith; and

a primary actuator operably associated with the support structure for
driving the arm portions relative to one another in response to an electrical activation
of the primary actuator, and a secondary actuator operably associated with each
secondary portion for driving each secondary portion between an opened position and
a closed position through an actuator-movement-amplification portion in response to
an electrical activation of the secondary actuator, each of the actuators being operable
independently of one another.

29. (New) The apparatus of claim 28, wherein the
actuator-movement-amplification portion of the support structure further comprises:
a rigid, non-flexing force transfer portion of the secondary portion of
the support structure located in opposition to an open end of a rigid, non-flexing

C-shaped web portion of the secondary portion of the support structure for supporting the corresponding secondary actuator therebetween; and hinge portions connecting the force transfer portion to the arm portions and the C-shaped web portion of the secondary portion of the support structure, one pair of hinge portions extending between the force transfer member portion and each arm portion of the secondary portion of the support structure, and another pair of hinge portions extending between the force transfer member portion and each side portion of the secondary portion of the support structure.

30. (New) An apparatus comprising:
a support structure having first and second arm portions movable relative to one another, and a secondary portion located on an outer end of each arm portion for movement therewith; and

a primary actuator operably associated with the support structure for driving the arm portions relative to one another in response to an electrical activation of the primary actuator, and a secondary actuator operably associated with each secondary portion for driving each secondary portion between an opened position and a closed position in response to an electrical activation of the secondary actuator, each of the actuators being operable independently of one another, wherein at least one of the primary and secondary actuators operates through an actuator-movement-amplification portion of the support structure.

31. (New) The apparatus of claim 30, wherein the at least one actuator-movement-amplification portion of the support structure further comprises:

a rigid, non-flexing force transfer portion located in opposition to an open end of a rigid, non-flexing C-shaped web portion for supporting the corresponding actuator therebetween; and

hinge portions connecting the force transfer portion to the arm portions and the C-shaped web portion, one pair of hinge portions extending between the force transfer member portion and each arm portion, and another pair of hinge portions extending between the force transfer member portion and each side portion.